

Problem for 2008 June

Proposed by Dan Jurca

Recall that the vector "cross product" $\mathbf{a} \times \mathbf{b}$ in \mathbf{R}^3 is not associative. For example

$$\mathbf{i} \times (\mathbf{i} \times \mathbf{j}) = \mathbf{i} \times \mathbf{k} = -\mathbf{j}, \text{ but}$$

$$(\mathbf{i} \times \mathbf{i}) \times \mathbf{j} = \mathbf{0} \times \mathbf{j} = \mathbf{0}.$$

So for vectors \mathbf{a} and \mathbf{b} in \mathbf{R}^3 let

$$V_1(\mathbf{a}, \mathbf{b}) = \{ \mathbf{x} \in \mathbf{R}^3 \mid \mathbf{x} \times (\mathbf{a} \times \mathbf{b}) = (\mathbf{x} \times \mathbf{a}) \times \mathbf{b} \}$$

$$V_2(\mathbf{a}, \mathbf{b}) = \{ \mathbf{x} \in \mathbf{R}^3 \mid \mathbf{a} \times (\mathbf{x} \times \mathbf{b}) = (\mathbf{a} \times \mathbf{x}) \times \mathbf{b} \}$$

$$V_3(\mathbf{a}, \mathbf{b}) = \{ \mathbf{x} \in \mathbf{R}^3 \mid \mathbf{a} \times (\mathbf{b} \times \mathbf{x}) = (\mathbf{a} \times \mathbf{b}) \times \mathbf{x} \}.$$

1. Prove that $\mathbf{a}, \mathbf{b} \in \mathbf{R}^3 \Rightarrow V_i(\mathbf{a}, \mathbf{b})$ is a subspace of \mathbf{R}^3 , $i=1,2,3$.
2. Prove that $\mathbf{a}, \mathbf{b} \in \mathbf{R}^3 \Rightarrow V_1(\mathbf{a}, \mathbf{b}) = V_3(\mathbf{b}, \mathbf{a})$.
3. Prove that $\mathbf{a} \in \mathbf{R}^3 \Rightarrow V_2(\mathbf{a}, \mathbf{a}) = \mathbf{R}^3$.
4. What are the subspaces $V_i(\mathbf{a}, \mathbf{0})$, $i=1,2,3$?
5. If $\mathbf{a} \neq \mathbf{0}$, what is the subspace $V_3(\mathbf{a}, \mathbf{a})$?
6. What is the subspace $V_3(\mathbf{i}, \mathbf{j})$?
7. What is the subspace $V_3(\mathbf{j}, \mathbf{i})$?
8. What is the subspace $V_3(\mathbf{i} + \mathbf{j}, \mathbf{i})$?
9. Show that $\mathbf{a}, \mathbf{b} \in \mathbf{R}^3 \Rightarrow V_i(\mathbf{a}, \mathbf{b}) \neq \{\mathbf{0}\}$, $i=1,2,3$.

Solution by the proposer

- 1.

Obviously $\mathbf{0}$, the zero vector, is in each $V_i(\mathbf{a}, \mathbf{b})$, so each is a nonempty subset of \mathbf{R}^3 . If $\mathbf{x} \in V_1(\mathbf{a}, \mathbf{b})$ and $\mathbf{y} \in V_1(\mathbf{a}, \mathbf{b})$, then

$$\begin{aligned}(\mathbf{x} + \mathbf{y}) \times (\mathbf{a} \times \mathbf{b}) &= (\mathbf{x} \times (\mathbf{a} \times \mathbf{b})) + (\mathbf{y} \times (\mathbf{a} \times \mathbf{b})) \\ &= ((\mathbf{x} \times \mathbf{a}) \times \mathbf{b}) + ((\mathbf{y} \times \mathbf{a}) \times \mathbf{b}) \\ &= ((\mathbf{x} \times \mathbf{a}) + (\mathbf{y} \times \mathbf{a})) \times \mathbf{b} \\ &= ((\mathbf{x} + \mathbf{y}) \times \mathbf{a}) \times \mathbf{b},\end{aligned}$$

so that $\mathbf{x} + \mathbf{y} \in V_1(\mathbf{a}, \mathbf{b})$. If $k \in \mathbf{R}$ and $\mathbf{x} \in V_1(\mathbf{a}, \mathbf{b})$, then

$$\begin{aligned}(k\mathbf{x}) \times (\mathbf{a} \times \mathbf{b}) &= k \times (\mathbf{x} \times (\mathbf{a} \times \mathbf{b})) \\ &= k((\mathbf{x} \times \mathbf{a}) \times \mathbf{b}) \\ &= (k(\mathbf{x} \times \mathbf{a})) \times \mathbf{b} \\ &= ((k\mathbf{x}) \times \mathbf{a}) \times \mathbf{b},\end{aligned}$$

so that $k\mathbf{x} \in V_1(\mathbf{a}, \mathbf{b})$. Hence $V_1(\mathbf{a}, \mathbf{b})$ is a subspace of \mathbf{R}^3 ; and similarly $V_2(\mathbf{a}, \mathbf{b})$ and $V_3(\mathbf{a}, \mathbf{b})$ are subspaces of \mathbf{R}^3 .

2.

If $\mathbf{x} \in V_1(\mathbf{a}, \mathbf{b})$, then $\mathbf{x} \times (\mathbf{a} \times \mathbf{b}) = (\mathbf{x} \times \mathbf{a}) \times \mathbf{b}$; hence

$$\begin{aligned}\mathbf{b} \times (\mathbf{a} \times \mathbf{x}) &= -\mathbf{b} \times (\mathbf{x} \times \mathbf{a}) \\ &= (\mathbf{x} \times \mathbf{a}) \times \mathbf{b} \\ &= \mathbf{x} \times (\mathbf{a} \times \mathbf{b}) \\ &= -(\mathbf{a} \times \mathbf{b}) \times \mathbf{x} \\ &= (\mathbf{b} \times \mathbf{a}) \times \mathbf{x},\end{aligned}$$

so that $\mathbf{x} \in V_3(\mathbf{b}, \mathbf{a})$, and $V_1(\mathbf{a}, \mathbf{b}) \subset V_3(\mathbf{b}, \mathbf{a})$. Similarly $V_3(\mathbf{b}, \mathbf{a}) \subset V_1(\mathbf{a}, \mathbf{b})$, whence $V_1(\mathbf{a}, \mathbf{b}) = V_3(\mathbf{b}, \mathbf{a})$.

3.

$\mathbf{x} \in \mathbf{R}^3 \Rightarrow \mathbf{a} \times (\mathbf{x} \times \mathbf{a}) = -(\mathbf{x} \times \mathbf{a}) \times \mathbf{a} = (\mathbf{a} \times \mathbf{x}) \times \mathbf{a}$, so that $\mathbf{x} \in V_2(\mathbf{a}, \mathbf{a})$; hence $\mathbf{R}^3 \subset V_2(\mathbf{a}, \mathbf{a})$, so $V_2(\mathbf{a}, \mathbf{a}) = \mathbf{R}^3$.

4.

Since $\mathbf{x} \in \mathbf{R}^3 \Rightarrow \mathbf{x} \times (\mathbf{a} \times \mathbf{0}) = \mathbf{x} \times \mathbf{0} = \mathbf{0} = (\mathbf{x} \times \mathbf{a}) \times \mathbf{0}$, $\mathbf{x} \in V_1(\mathbf{a}, \mathbf{0})$, and $V_1(\mathbf{a}, \mathbf{0}) = \mathbf{R}^3$. Similarly $V_2(\mathbf{a}, \mathbf{0}) = \mathbf{R}^3$ and $V_3(\mathbf{a}, \mathbf{0}) = \mathbf{R}^3$.

5.

$\mathbf{x} \in V_3(\mathbf{a}, \mathbf{a}) \Rightarrow \mathbf{a} \times (\mathbf{a} \times \mathbf{x}) = (\mathbf{a} \times \mathbf{a}) \times \mathbf{x} = \mathbf{0} \times \mathbf{x} = \mathbf{0}$; it follows that $(\mathbf{a} \cdot \mathbf{x})\mathbf{a} - (\mathbf{a} \cdot \mathbf{a})\mathbf{x} = \mathbf{0}$, so that (since $\mathbf{a} \neq \mathbf{0}$) $\mathbf{x} = (\mathbf{a} \cdot \mathbf{x})\mathbf{a} / (\mathbf{a} \cdot \mathbf{a})$; i.e., $\mathbf{x} = k\mathbf{a}$ for some $k \in \mathbf{R}$. Conversely, if $\mathbf{x} = k\mathbf{a}$, then $\mathbf{a} \times (\mathbf{a} \times \mathbf{x}) = \mathbf{a} \times (\mathbf{a} \times k\mathbf{a}) = \mathbf{0} = \mathbf{0} \times \mathbf{x} = (\mathbf{a} \times \mathbf{a}) \times \mathbf{x}$, and $\mathbf{x} \in V_3(\mathbf{a}, \mathbf{a})$. Hence $\mathbf{a} \neq \mathbf{0} \Rightarrow V_3(\mathbf{a}, \mathbf{a}) = \mathbf{R}\mathbf{a}$.

6.

Suppose $\mathbf{x} = x_1\mathbf{i} + x_2\mathbf{j} + x_3\mathbf{k}$ and $\mathbf{x} \in V_3(\mathbf{i}, \mathbf{j})$. Then $\mathbf{i} \times (\mathbf{j} \times (x_1\mathbf{i} + x_2\mathbf{j} + x_3\mathbf{k})) = (\mathbf{i} \times \mathbf{j}) \times (x_1\mathbf{i} + x_2\mathbf{j} + x_3\mathbf{k})$. Therefore $\mathbf{i} \times (-x_1\mathbf{k} + x_3\mathbf{i}) = \mathbf{k} \times (x_1\mathbf{i} + x_2\mathbf{j} + x_3\mathbf{k})$, so $x_1\mathbf{j} = x_1\mathbf{j} - x_2\mathbf{i}$. Therefore $x_2 = 0$ and $\mathbf{x} = x_1\mathbf{i} + x_3\mathbf{k}$. Conversely, $\mathbf{i} \times (\mathbf{j} \times (x_1\mathbf{i} + x_3\mathbf{k})) = \mathbf{i} \times (-x_1\mathbf{k} + x_3\mathbf{i}) = x_1\mathbf{j} = x_1(\mathbf{k} \times \mathbf{i}) + \mathbf{0} = \mathbf{k} \times (x_1\mathbf{i} + x_3\mathbf{k}) = (\mathbf{i} \times \mathbf{j}) \times (x_1\mathbf{i} + x_3\mathbf{k})$, so $x_1\mathbf{i} + x_3\mathbf{k} \in V_3(\mathbf{i}, \mathbf{j})$. Therefore $V_3(\mathbf{i}, \mathbf{j}) = \mathbf{R}\mathbf{i} \oplus \mathbf{R}\mathbf{k}$.

7.

If $\mathbf{x} = x_1\mathbf{i} + x_2\mathbf{j} + x_3\mathbf{k} \in V_3(\mathbf{j}, \mathbf{i})$, then

$\mathbf{j} \times (\mathbf{i} \times (x_1\mathbf{i} + x_2\mathbf{j} + x_3\mathbf{k})) = \mathbf{j} \times (x_2\mathbf{k} - x_3\mathbf{j}) = x_2\mathbf{i} = (\mathbf{j} \times \mathbf{i}) \times (x_1\mathbf{i} + x_2\mathbf{j} + x_3\mathbf{k}) = -\mathbf{k} \times (x_1\mathbf{i} + x_2\mathbf{j} + x_3\mathbf{k}) = -x_1\mathbf{j} + x_2\mathbf{i}$, so that $x_1 = 0$ and $\mathbf{x} = x_2\mathbf{j} + x_3\mathbf{k}$. Conversely, if $\mathbf{x} = x_2\mathbf{j} + x_3\mathbf{k}$, then

$\mathbf{j} \times (\mathbf{i} \times \mathbf{x}) = \mathbf{j} \times (\mathbf{i} \times (x_2\mathbf{j} + x_3\mathbf{k})) = \mathbf{j} \times (x_2\mathbf{k} - x_3\mathbf{j}) = x_2\mathbf{i} = -\mathbf{k} \times (x_2\mathbf{j} + x_3\mathbf{k}) = (\mathbf{j} \times \mathbf{i}) \times (x_2\mathbf{j} + x_3\mathbf{k})$, so $\mathbf{x} \in V_3(\mathbf{j}, \mathbf{i})$. Hence $V_3(\mathbf{j}, \mathbf{i}) = \mathbf{R}\mathbf{j} \oplus \mathbf{R}\mathbf{k}$.

8.

If $\mathbf{x} = x_1\mathbf{i} + x_2\mathbf{j} + x_3\mathbf{k}$ and $\mathbf{x} \in V_3(\mathbf{i} + \mathbf{j}, \mathbf{i})$, then we find

$(\mathbf{i} + \mathbf{j}) \times (\mathbf{i} \times (x_1\mathbf{i} + x_2\mathbf{j} + x_3\mathbf{k})) = (\mathbf{i} + \mathbf{j}) \times (x_2\mathbf{k} - x_3\mathbf{j}) = -x_2\mathbf{j} - x_3\mathbf{k} + x_2\mathbf{i} = x_2\mathbf{i} - x_2\mathbf{j} - x_3\mathbf{k}$; and

$((\mathbf{i} + \mathbf{j}) \times \mathbf{i}) \times (x_1\mathbf{i} + x_2\mathbf{j} + x_3\mathbf{k}) = -\mathbf{k} \times (x_1\mathbf{i} + x_2\mathbf{j} + x_3\mathbf{k}) = -x_1\mathbf{j} + x_2\mathbf{i} = x_2\mathbf{i} - x_1\mathbf{j}$. Therefore $x_1 = x_2$ and $x_3 = 0$, so that $\mathbf{x} = k(\mathbf{i} + \mathbf{j})$ for some $k \in \mathbf{R}$. Conversely,

$(\mathbf{i} + \mathbf{j}) \times (\mathbf{i} \times k(\mathbf{i} + \mathbf{j})) = k(\mathbf{i} + \mathbf{j}) \times \mathbf{k} = k(-\mathbf{j} + \mathbf{i}) = -k(\mathbf{j} - \mathbf{i}) = -k\mathbf{k} \times (\mathbf{i} + \mathbf{j}) = ((\mathbf{i} + \mathbf{j}) \times \mathbf{i}) \times k(\mathbf{i} + \mathbf{j})$, so $k(\mathbf{i} + \mathbf{j}) \in V_3(\mathbf{i} + \mathbf{j}, \mathbf{i})$. Thus $V_3(\mathbf{i} + \mathbf{j}, \mathbf{i}) = \mathbf{R}(\mathbf{i} + \mathbf{j})$.

9.

Suppose $\mathbf{a} = a_1\mathbf{i} + a_2\mathbf{j} + a_3\mathbf{k}$ and $\mathbf{b} = b_1\mathbf{i} + b_2\mathbf{j} + b_3\mathbf{k}$. Then by a straightforward computation we find that $\mathbf{x} \in V_1(\mathbf{a}, \mathbf{b})$ if and only if $M_1\mathbf{x} = \mathbf{0}$, $\mathbf{x} \in V_2(\mathbf{a}, \mathbf{b})$ if and only if $M_2\mathbf{x} = \mathbf{0}$, and $\mathbf{x} \in V_3(\mathbf{a}, \mathbf{b})$ if and only if $M_3\mathbf{x} = \mathbf{0}$ where M_1 , M_2 , and M_3 are the following matrices.

$$M_1 = \begin{bmatrix} a_2b_2 + a_3b_3 & -a_2b_1 & -a_3b_1 \\ -a_1b_2 & a_1b_1 + a_3b_3 & -a_3b_2 \\ -a_1b_3 & -a_2b_3 & a_1b_1 + a_2b_2 \end{bmatrix}$$

$$M_2 = \begin{bmatrix} 0 & a_1b_2 - a_2b_1 & a_1b_3 - a_3b_1 \\ -a_1b_2 + a_2b_1 & 0 & a_2b_3 - a_3b_2 \\ -a_1b_3 + a_3b_1 & -a_2b_3 + a_3b_2 & 0 \end{bmatrix}$$

$$M_3 = \begin{bmatrix} a_2b_2 + a_3b_3 & -a_1b_2 & -a_1b_3 \end{bmatrix}$$

$$\begin{bmatrix} -a_2b_1 & a_1b_1+a_3b_3 & -a_2b_3 \\ -a_3b_1 & -a_3b_2 & a_1b_1+a_2b_2 \end{bmatrix}$$

By another straightforward computation one finds that each of M_1 , M_2 , and M_3 is a singular matrix; hence for each \mathbf{a} and \mathbf{b} there exists a nonzero vector in each of $V_1(\mathbf{a},\mathbf{b})$, $V_2(\mathbf{a},\mathbf{b})$, and $V_3(\mathbf{a},\mathbf{b})$.

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