

Problem for 2009 September

Communicated by Dan Jurca

An observer at the point $(a, b, c) \neq (0, 0, 0)$ in \mathbf{R}^3 looks toward the origin; what angles will the observer see between the positive coordinate axes?

For example, an observer at the point $(1, 1, 1)$ looking toward the origin will see angles of $2\pi/3 = 120^\circ$ between the axes.

Solution by Dan Jurca

Let $\mathbf{n} = a\mathbf{i} + b\mathbf{j} + c\mathbf{k}$; for each vector \mathbf{v} in \mathbf{R}^3 we have the projection of \mathbf{v} onto Π , the plane with equation $ax + by + cz = 0$ normal to \mathbf{n} and passing through the origin, by

$$\text{proj}_{\Pi}\mathbf{v} = \mathbf{v} - \frac{\mathbf{n} \cdot \mathbf{v}}{\|\mathbf{n}\|^2}\mathbf{n}.$$

With $r^2 = \|\mathbf{n}\|^2 = a^2 + b^2 + c^2$ and

$$\begin{aligned}\mathbf{x} &= \text{proj}_{\Pi}\mathbf{i} = \mathbf{i} - \frac{a}{r^2}\mathbf{n} \\ \mathbf{y} &= \text{proj}_{\Pi}\mathbf{j} = \mathbf{j} - \frac{b}{r^2}\mathbf{n} \\ \mathbf{z} &= \text{proj}_{\Pi}\mathbf{k} = \mathbf{k} - \frac{c}{r^2}\mathbf{n};\end{aligned}$$

we interpret the problem to mean finding the angles $\theta_{\mathbf{x}\mathbf{y}}$, $\theta_{\mathbf{y}\mathbf{z}}$, and $\theta_{\mathbf{z}\mathbf{x}}$, between the vectors \mathbf{x} and \mathbf{y} , \mathbf{y} and \mathbf{z} , and \mathbf{z} and \mathbf{x} , respectively. To do this we compute

$$\begin{aligned}\mathbf{x} \cdot \mathbf{y} &= \mathbf{i} \cdot \mathbf{j} - \frac{b}{r^2}\mathbf{i} \cdot \mathbf{n} - \frac{a}{r^2}\mathbf{n} \cdot \mathbf{j} + \frac{ab}{(r^2)^2}\mathbf{n} \cdot \mathbf{n} = \frac{-ba - ab + ab}{r^2} = -\frac{ab}{r^2} \\ \mathbf{y} \cdot \mathbf{z} &= \mathbf{j} \cdot \mathbf{k} - \frac{c}{r^2}\mathbf{j} \cdot \mathbf{n} - \frac{b}{r^2}\mathbf{n} \cdot \mathbf{k} + \frac{bc}{(r^2)^2}\mathbf{n} \cdot \mathbf{n} = \frac{-cb - bc + bc}{r^2} = -\frac{bc}{r^2} \\ \mathbf{z} \cdot \mathbf{x} &= \mathbf{k} \cdot \mathbf{i} - \frac{a}{r^2}\mathbf{k} \cdot \mathbf{n} - \frac{c}{r^2}\mathbf{n} \cdot \mathbf{i} + \frac{ca}{(r^2)^2}\mathbf{n} \cdot \mathbf{n} = \frac{-ac - ca + ca}{r^2} = -\frac{ca}{r^2} \\ \|\mathbf{x}\|^2 &= \mathbf{x} \cdot \mathbf{x} = \mathbf{i} \cdot \mathbf{i} - \frac{a}{r^2}\mathbf{i} \cdot \mathbf{n} - \frac{a}{r^2}\mathbf{n} \cdot \mathbf{i} + \frac{a^2}{(r^2)^2}\mathbf{n} \cdot \mathbf{n} = \frac{r^2}{r^2} - \frac{2a^2}{r^2} + \frac{a^2}{r^2} = \frac{r^2 - a^2}{r^2} = \frac{b^2 + c^2}{r^2} \\ \|\mathbf{y}\|^2 &= \mathbf{y} \cdot \mathbf{y} = \mathbf{j} \cdot \mathbf{j} - \frac{b}{r^2}\mathbf{j} \cdot \mathbf{n} - \frac{b}{r^2}\mathbf{n} \cdot \mathbf{j} + \frac{b^2}{(r^2)^2}\mathbf{n} \cdot \mathbf{n} = \frac{r^2}{r^2} - \frac{2b^2}{r^2} + \frac{b^2}{r^2} = \frac{r^2 - b^2}{r^2} = \frac{c^2 + a^2}{r^2} \\ \|\mathbf{z}\|^2 &= \mathbf{z} \cdot \mathbf{z} = \mathbf{k} \cdot \mathbf{k} - \frac{c}{r^2}\mathbf{k} \cdot \mathbf{n} - \frac{c}{r^2}\mathbf{n} \cdot \mathbf{k} + \frac{c^2}{(r^2)^2}\mathbf{n} \cdot \mathbf{n} = \frac{r^2}{r^2} - \frac{2c^2}{r^2} + \frac{c^2}{r^2} = \frac{r^2 - c^2}{r^2} = \frac{a^2 + b^2}{r^2}.\end{aligned}$$

We have then, from $\mathbf{x} \cdot \mathbf{y} = \|\mathbf{x}\|\|\mathbf{y}\| \cos \theta_{\mathbf{x}\mathbf{y}}$ if $\mathbf{x} \neq \mathbf{0}$ and $\mathbf{y} \neq \mathbf{0}$, etc.,

$$\begin{aligned}\theta_{\mathbf{x}\mathbf{y}} &\begin{cases} = \cos^{-1} \left(-\frac{ab}{\sqrt{(b^2 + c^2)(c^2 + a^2)}} \right) & \text{if } c \neq 0 \text{ or } (a \neq 0 \text{ and } b \neq 0) \\ \text{not defined} & \text{otherwise,} \end{cases} \\ \theta_{\mathbf{y}\mathbf{z}} &\begin{cases} = \cos^{-1} \left(-\frac{bc}{\sqrt{(c^2 + a^2)(a^2 + b^2)}} \right) & \text{if } a \neq 0 \text{ or } (c \neq 0 \text{ and } b \neq 0) \\ \text{not defined} & \text{otherwise, and} \end{cases} \\ \theta_{\mathbf{z}\mathbf{x}} &\begin{cases} = \cos^{-1} \left(-\frac{ca}{\sqrt{(a^2 + b^2)(b^2 + c^2)}} \right) & \text{if } b \neq 0 \text{ or } (a \neq 0 \text{ and } c \neq 0) \\ \text{not defined} & \text{otherwise.} \end{cases}\end{aligned}$$

Also solved by Jan van Delden (the Netherlands) and Grant Morgan